

Free Surface Hydrodynamics 2DH and 3D Shallow Water Equations

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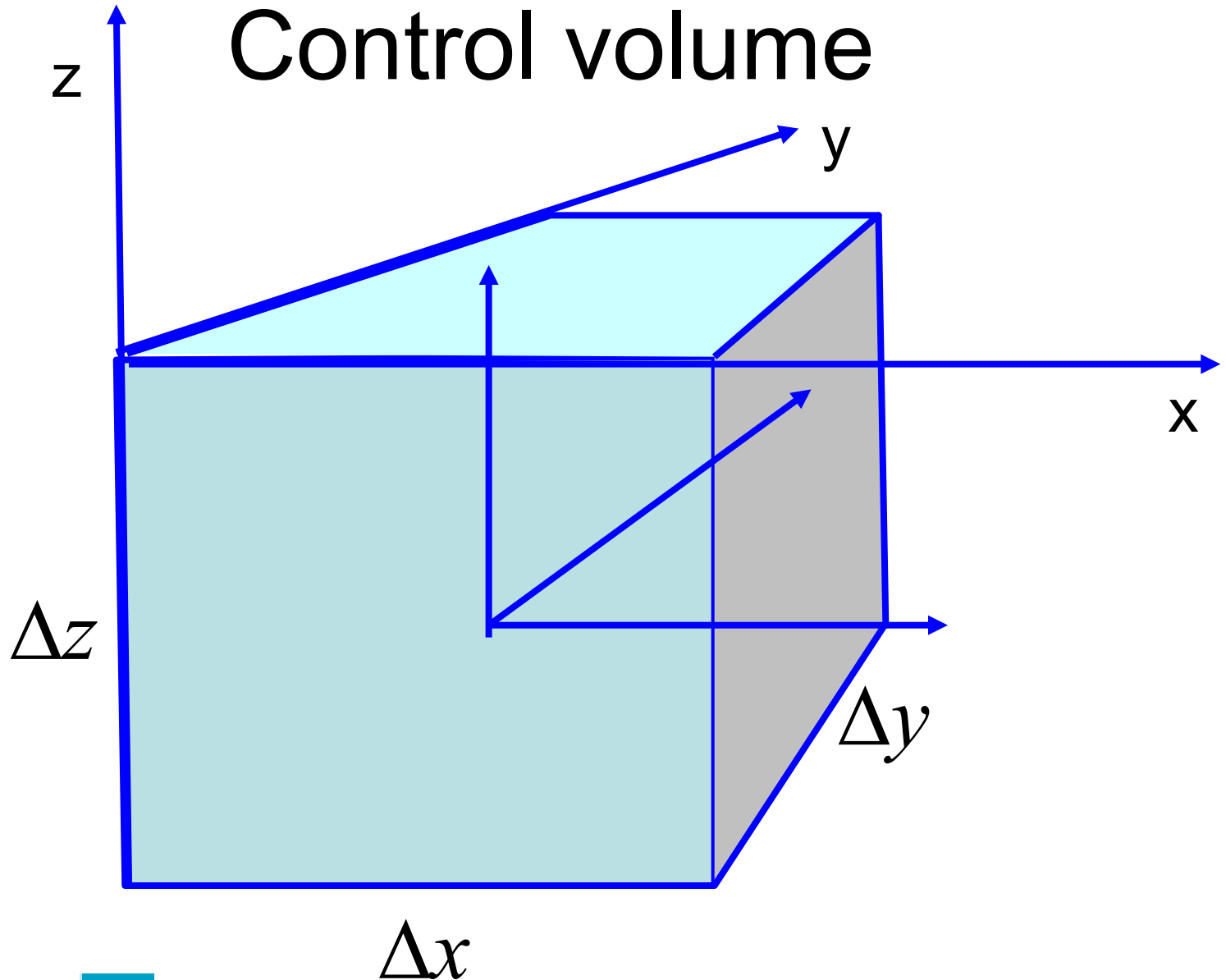


Contents

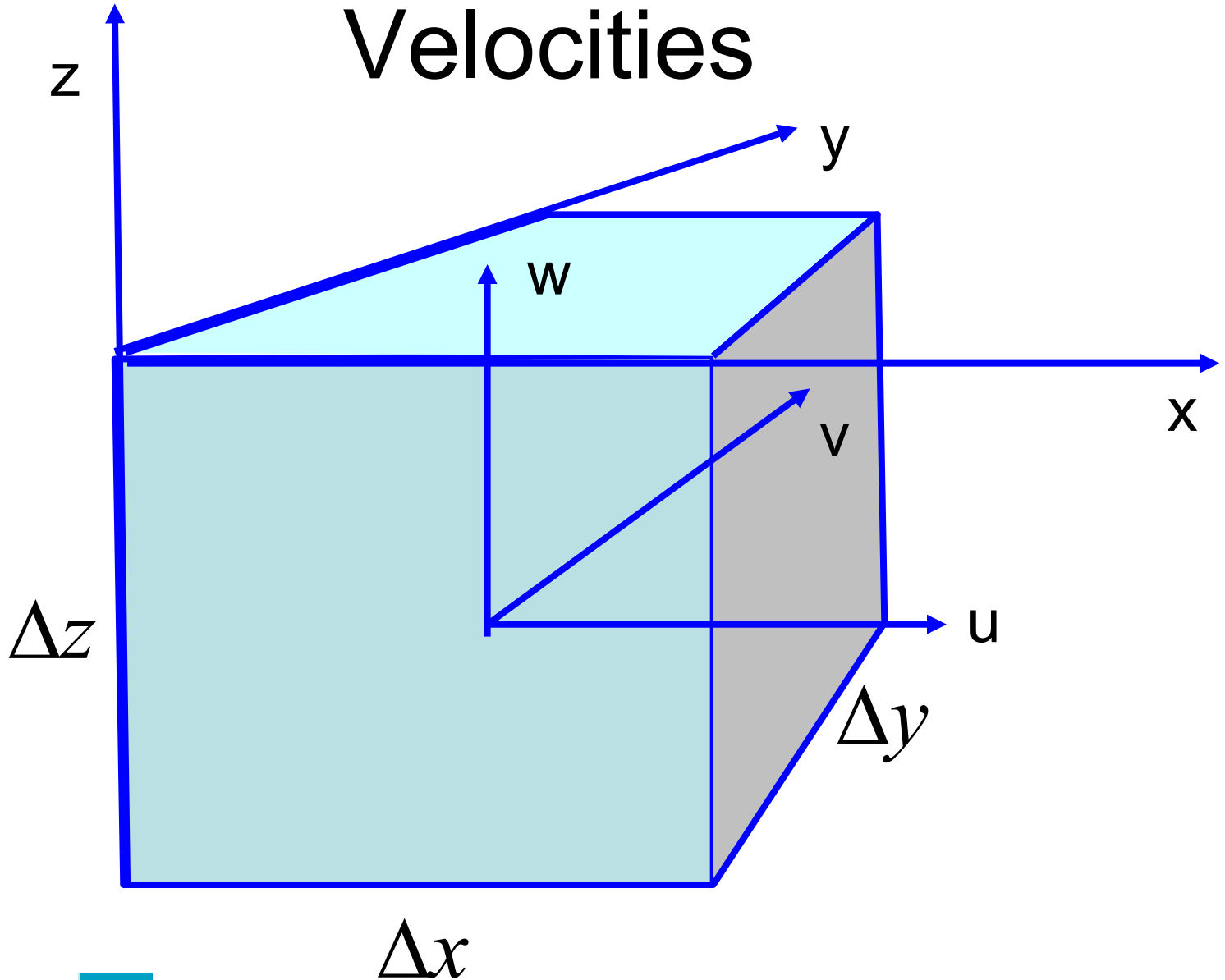
- Main assumptions and derivation from Navier-Stokes Equations
- Some simple limit cases
- (A bit on) numerical models
- Typical applications



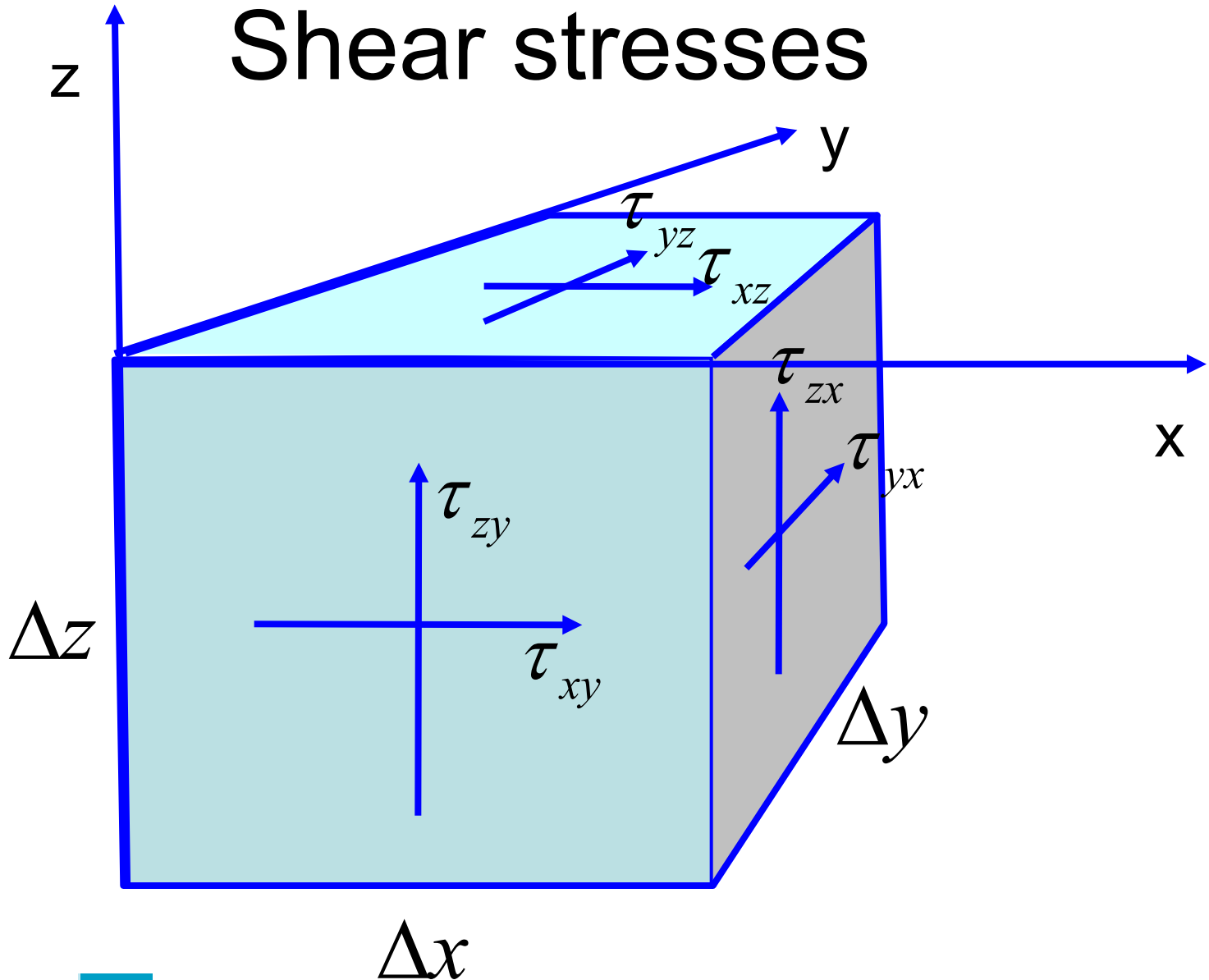
Control volume



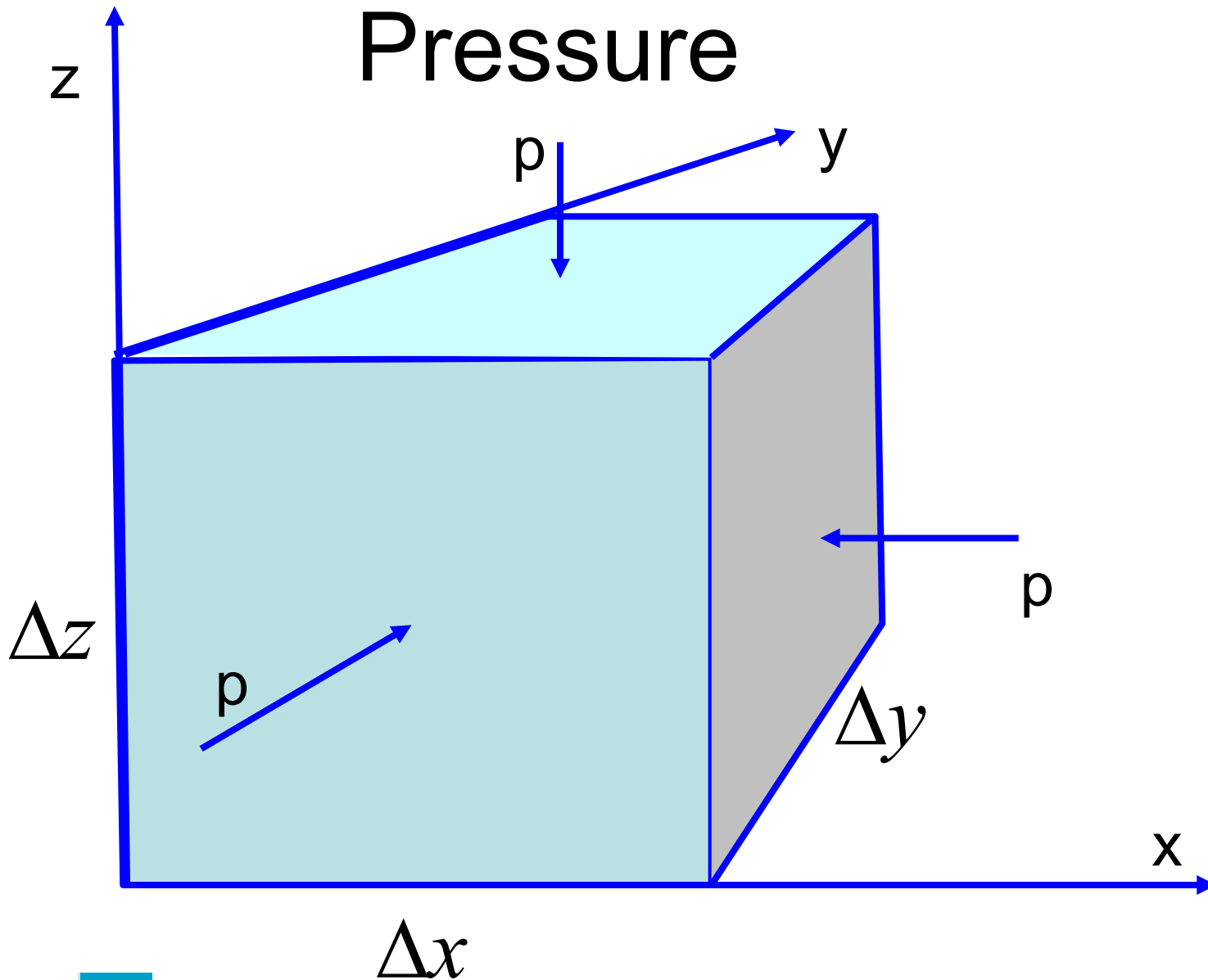
Velocities



Shear stresses



Pressure



Momentum balance

$$\frac{du}{dt} - f_{cor}v = \frac{1}{\rho} \left(\frac{\partial \tau_{xy}}{\partial y} + \frac{\partial \tau_{xz}}{\partial z} - \frac{\partial p}{\partial x} \right)$$

$$\frac{dv}{dt} + f_{cor}u = \frac{1}{\rho} \left(\frac{\partial \tau_{yx}}{\partial x} + \frac{\partial \tau_{yz}}{\partial z} - \frac{\partial p}{\partial y} \right)$$

$$\frac{dw}{dt} = \frac{1}{\rho} \left(\frac{\partial \tau_{zx}}{\partial x} + \frac{\partial \tau_{zy}}{\partial y} - \frac{\partial p}{\partial z} \right) - g$$



Mass balance

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$



Assumption 1: incompressible flow

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$



Averaging momentum balance over short timescales

- Turbulence
 - Reynolds stresses
 - Approximated by turbulent shear stresses

$$\tau_{xy} = \rho V_h \frac{\partial u}{\partial y}, \quad \tau_{yx} = \rho V_h \frac{\partial v}{\partial x}, \quad \tau_{xz} = \rho V_v \frac{\partial u}{\partial z}, \quad \tau_{yz} = \rho V_v \frac{\partial v}{\partial z}$$

$$\tau_{zx} = \rho V_h \frac{\partial w}{\partial x}, \quad \tau_{zy} = \rho V_h \frac{\partial w}{\partial y}$$



Shallow water approximation

- Horizontal scales \gg vertical scales
- Vertical velocities \ll horizontal velocities
- Neglect vertical acceleration

$$\frac{dw}{dt} = \frac{1}{\rho} \left(\frac{\partial \tau_{zx}}{\partial x} + \frac{\partial \tau_{zy}}{\partial y} - \frac{\partial p}{\partial z} \right) - g \Rightarrow$$

$$\frac{\partial p}{\partial z} = -\rho g$$



Hydrostatic pressure

- Inhomogeneous (density not constant):

$$p = p_a + g \int_z^{\eta} \rho dz$$

- Homogeneous (density constant):

$$p = p_a + \rho g(\eta - z)$$



Shallow Water Equations (3D)

$$\frac{du}{dt} - f_{cor}v = \frac{\partial}{\partial y} \left(v_h \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(v_v \frac{\partial u}{\partial z} \right) - \frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{w_x}{\rho}$$

$$\frac{dv}{dt} + f_{cor}u = \frac{\partial}{\partial x} \left(v_h \frac{\partial v}{\partial x} \right) + \frac{\partial}{\partial z} \left(v_v \frac{\partial v}{\partial z} \right) - \frac{1}{\rho} \frac{\partial p}{\partial y} + \frac{w_y}{\rho}$$

Acceleration

Coriolis

Horizontal
diffusion

Vertical
diffusion

Horizontal
pressure
gradient

Wave
forcing



Boundary conditions

$$w = 0$$

$$\rho \nu_v \frac{\partial u}{\partial z} = \tau_{bx}$$

$$\rho \nu_v \frac{\partial v}{\partial z} = \tau_{by}$$

Bottom ($z = -d$)

$$w = \frac{\partial \eta}{\partial t}$$

$$\rho \nu_v \frac{\partial u}{\partial z} = \tau_{sx}$$

$$\rho \nu_v \frac{\partial v}{\partial z} = \tau_{sy}$$

Surface ($z = \eta$)



Depth-averaged mass balance

$$\int_{-d}^{\eta} \frac{\partial u}{\partial x} dz + \int_{-d}^{\eta} \frac{\partial v}{\partial y} dz + \int_{-d}^{\eta} \frac{\partial w}{\partial z} dz = 0 \Rightarrow$$

$$\Rightarrow \frac{\partial h\bar{u}}{\partial x} + \frac{\partial h\bar{v}}{\partial y} + w(\eta) - w(-h) = 0 \Rightarrow$$

$$\Rightarrow \boxed{\frac{\partial h\bar{u}}{\partial x} + \frac{\partial h\bar{v}}{\partial y} + \frac{\partial \eta}{\partial t} = 0}$$



From moving to fixed frame of reference

$$u = f(t, x, y, z)$$

$$\frac{du}{dt} = \frac{\partial u}{\partial t} \frac{dt}{dt} + \frac{\partial u}{\partial x} \frac{dx}{dt} + \frac{\partial u}{\partial y} \frac{dy}{dt} + \frac{\partial u}{\partial z} \frac{dz}{dt}$$

$$\frac{du}{dt} = \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}$$



From moving to fixed frame of reference

$$\frac{du}{dt} = \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}$$
$$\frac{dv}{dt} = \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z}$$

Inertia

Advection

Shallow Water Equations (3D)

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} - f_{cor} v = \frac{\partial}{\partial y} \left(\nu_h \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left(\nu_v \frac{\partial u}{\partial z} \right) - \frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{w_x}{\rho}$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} + f_{cor} u = \frac{\partial}{\partial x} \left(\nu_h \frac{\partial v}{\partial x} \right) + \frac{\partial}{\partial z} \left(\nu_v \frac{\partial v}{\partial z} \right) - \frac{1}{\rho} \frac{\partial p}{\partial y} + \frac{w_y}{\rho}$$

$$\frac{\partial h\bar{u}}{\partial x} + \frac{\partial h\bar{v}}{\partial x} + \frac{\partial \eta}{\partial t} = 0$$

$$p = p_a + \int_z^{\eta} \rho g dz$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$



Depth-averaged momentum balance

$$\frac{\partial \bar{u}}{\partial t} + \bar{u} \frac{\partial \bar{u}}{\partial x} + \bar{v} \frac{\partial \bar{u}}{\partial y} - f_{cor} \bar{v} = \frac{\partial}{\partial y} D_h \frac{\partial \bar{u}}{\partial y} + \frac{\tau_{sx}}{\rho h} - \frac{\tau_{bx}}{\rho h} - \frac{1}{\rho} \frac{\partial p_a}{\partial x} - g \frac{\partial \eta}{\partial x} + \frac{F_x}{\rho h}$$

$$\frac{\partial \bar{v}}{\partial t} + \bar{u} \frac{\partial \bar{v}}{\partial x} + \bar{v} \frac{\partial \bar{v}}{\partial y} + f_{cor} \bar{u} = \frac{\partial}{\partial x} D_h \frac{\partial \bar{v}}{\partial x} + \frac{\tau_{sy}}{\rho h} - \frac{\tau_{by}}{\rho h} - \frac{1}{\rho} \frac{\partial p_a}{\partial y} - g \frac{\partial \eta}{\partial y} + \frac{F_y}{\rho h}$$

Acceleration

Advection

Coriolis

Horizontal diffusion

Wind shear stress

Bed shear stress

Water level gradient

Wave forcing



Free Surface Hydrodynamics
2DH and 3D Shallow Water Equations
Simple limit cases

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Contents

- Stationary, uniform flow
- 1D tidal wave
- 1D St Venant equations
- Backwater curve
- Stationary wind setup
- Vertical profile of uniform, stationary flow



Limit case: stationary, uniform flow

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - f_{cor} v = \frac{\partial}{\partial y} D_h \frac{\partial u}{\partial y} + \frac{\tau_{sx}}{\rho h} - \frac{\tau_{bx}}{\rho h} - \frac{1}{\rho} \frac{\partial p_a}{\partial x} - g \frac{\partial \eta}{\partial x} + \frac{F_x}{\rho h}$$

$$\Rightarrow \frac{\tau_{bx}}{\rho h} = -g \frac{\partial \eta}{\partial x} \Rightarrow \tau_{bx} = -\rho g h \frac{\partial \eta}{\partial x}$$

Question: given Chezy law, how
can you compute velocity u ?



Chezy law

$$\tau_{bx} = -\rho g h \frac{\partial \eta}{\partial x}$$

$$\tau_{bx} = \rho g \frac{|u|u}{C^2}$$

$$\rho g \frac{|u|u}{C^2} = -\rho g h \frac{\partial \eta}{\partial x} \Rightarrow |u|u = -C^2 h \frac{\partial \eta}{\partial x} = C^2 h S$$

$$u = C \sqrt{hS} , S > 0$$



Limit case: 1D tidal wave

- Very long tidal wave in deep channel

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - f_{cor} v = \frac{\partial}{\partial y} D_h \frac{\partial u}{\partial y} + \frac{\tau_{sx}}{\rho h} - \frac{\tau_{bx}}{\rho h} - \frac{1}{\rho} \frac{\partial p_a}{\partial x} - g \frac{\partial \eta}{\partial x} + \frac{F_x}{\rho h}$$

$$\frac{\partial u}{\partial t} + g \frac{\partial \eta}{\partial x} = 0$$

$$\frac{\partial \eta}{\partial t} + h \frac{\partial u}{\partial x} = 0$$

From
continuity eq.



Limit case: 1D tidal wave

$$\frac{\partial u}{\partial t} + g \frac{\partial \eta}{\partial x} = 0$$

$$\frac{\partial \eta}{\partial t} + h \frac{\partial u}{\partial x} = 0$$

$$\eta = \hat{\eta} \cos(\omega t - kx)$$

$$u = \hat{u}_1 \cos(\omega t - kx)$$

$$\omega = \frac{2\pi}{T}, \quad k = \frac{2\pi}{L}$$

$$\frac{\partial \eta}{\partial t} = -\omega \hat{\eta} \sin(\omega t - kx)$$

$$\frac{\partial u}{\partial t} = -\omega \hat{u} \sin(\omega t - kx)$$

$$\frac{\partial \eta}{\partial x} = k \hat{\eta} \sin(\omega t - kx)$$

$$\frac{\partial u}{\partial x} = k \hat{u} \sin(\omega t - kx)$$

$$-\omega \hat{u} + gk \hat{\eta} = 0$$

$$-\omega \hat{\eta} + hk \hat{u} = 0$$



Shallow water wave celerity

- After substituting u in second equation:

$$\omega / k = c = \sqrt{gh} \quad \omega = \frac{2\pi}{T}, \quad k = \frac{2\pi}{L}$$

- First equation:

$$u = \frac{c}{h} \hat{\eta} = \sqrt{\frac{g}{h}} \hat{\eta} \cos(\omega t - kx)$$



How to use it

- Period T is given (approx. 12 hrs)
- Celerity c depends only on water depth
- Velocity u depends on water depth and tidal amplitude
- Example: given water depth of 20 m, tidal amplitude of 1 m, estimate celerity and amplitude of velocity



Limit case: 1D St Venant equations

- Neglect v velocity and all gradients with y

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - f_{cor} v = \frac{\partial}{\partial y} D_h \frac{\partial u}{\partial y} + \frac{\tau_{sx}}{\rho h} - \frac{\tau_{bx}}{\rho h} - \frac{1}{\rho} \frac{\partial p_a}{\partial x} - g \frac{\partial \eta}{\partial x} + \frac{F_x}{\rho h}$$

$$\frac{\partial \eta}{\partial t} + \frac{\partial hu}{\partial x} + \frac{\partial hv}{\partial y} = 0$$



Limit case: backwater curve

- St Venant + stationary: neglect d/dt

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - f_{cor} v = \frac{\partial}{\partial y} D_h \frac{\partial u}{\partial y} + \frac{\tau_{sx}}{\rho h} - \frac{\tau_{bx}}{\rho h} - \frac{1}{\rho} \frac{\partial p_a}{\partial x} - g \frac{\partial \eta}{\partial x} + \frac{F_x}{\rho h}$$

$$\frac{\partial \frac{1}{2} u^2}{\partial x} = - \frac{\tau_{bx}}{\rho h} - g \frac{\partial h}{\partial x} - g \frac{\partial z_b}{\partial x} \quad \eta = z_b + h$$

$$\frac{\partial \left(h + \frac{u^2}{2g} \right)}{\partial x} = - \frac{\tau_{bx}}{\rho g h} - \frac{\partial z_b}{\partial x}$$



Limit case: stationary wind setup

- Wind exerts surface shear stress
- If there is a closed boundary , the cross-shore velocity goes to zero
- Wind stress term is compensated by surface slope term

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - f_{cor} v = \frac{\partial}{\partial y} D_h \frac{\partial u}{\partial y} + \frac{\tau_{sx}}{\rho h} - \frac{\tau_{bx}}{\rho h} - \frac{1}{\rho} \frac{\partial p_a}{\partial x} - g \frac{\partial \eta}{\partial x} + \frac{F_x}{\rho h}$$

$$\frac{\partial \eta}{\partial x} = \frac{\tau_{sx}}{\rho g h} \Rightarrow \Delta \eta = \frac{\tau_{sx}}{\rho g h} \Delta x$$



Setup question

- Wind shear stress is 1 N/m^2
- Length of sea or lake is 100 km
- Water depth is 10 m
- How big is water level difference
- Is it different for a lake or a sea?



3D limit case: vertical profile of uniform, stationary flow

- Shear stress term balances pressure gradient term

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} + f_{cor} u = \frac{\partial}{\partial x} \left(\nu_h \frac{\partial v}{\partial x} \right) + \frac{\partial}{\partial z} \left(\nu_v \frac{\partial v}{\partial z} \right) - \frac{1}{\rho} \frac{\partial p}{\partial y} + \frac{w_y}{\rho}$$

- Pressure gradient given by surface slope term:

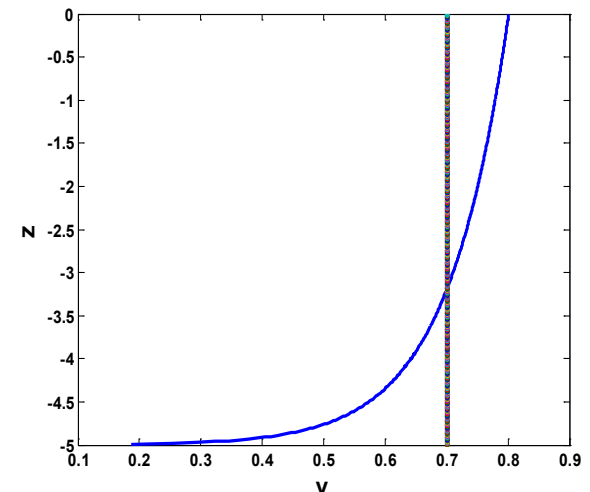
$$\frac{\partial}{\partial z} \left(\nu_v \frac{\partial v}{\partial z} \right) = g \frac{\partial \eta}{\partial y}$$

- Parabolic viscosity distribution

$$\nu_v = -K \nu_* z \frac{(h+z)}{h}$$

- Solution: logarithmic profile:

$$v = \frac{\nu_*}{K} \ln \frac{h+z}{z_0}$$



Why these analyses if you have numerical models?

- Numerical models can be wrong
- Need to understand the outcome
- Need to be able to check at least the order of magnitude of the outcome

